



RX 10





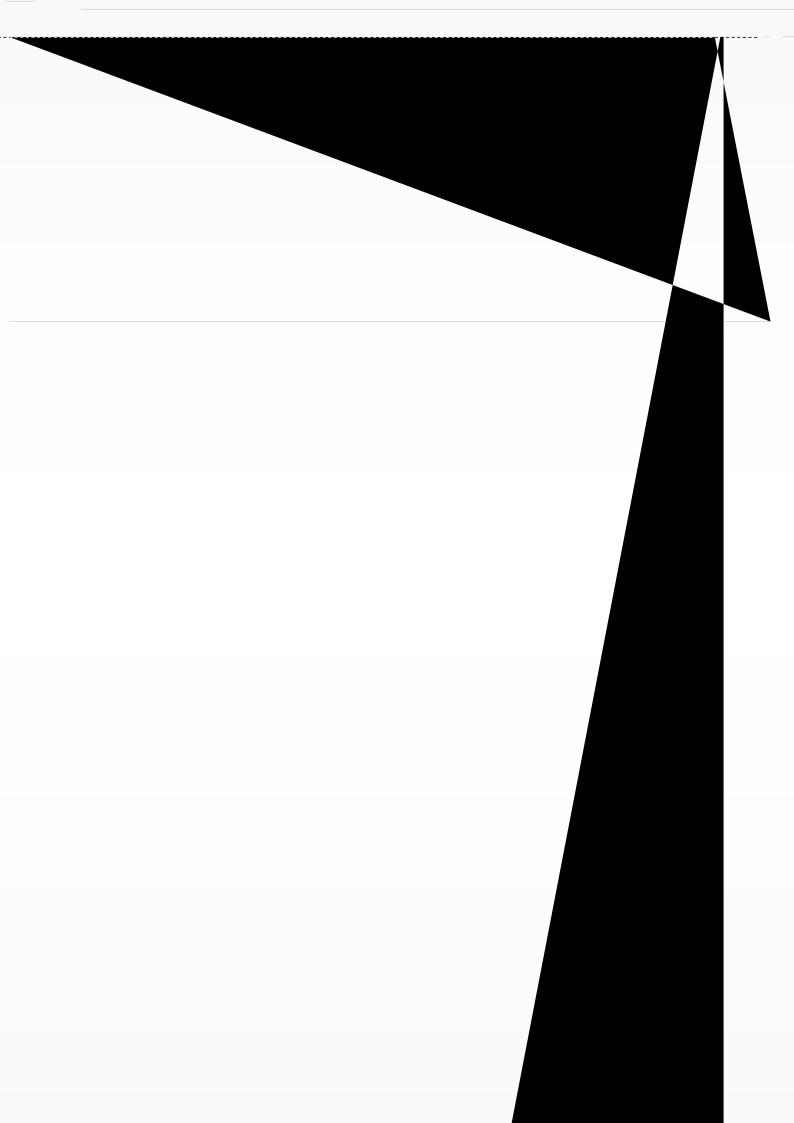






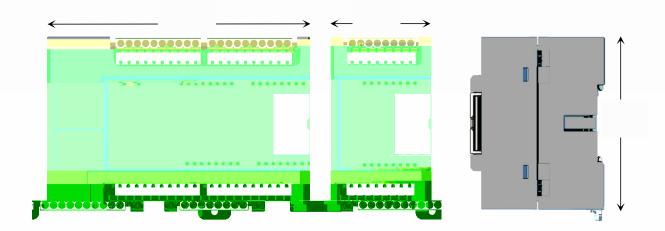




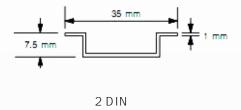


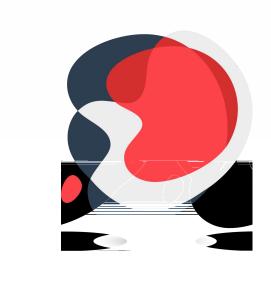


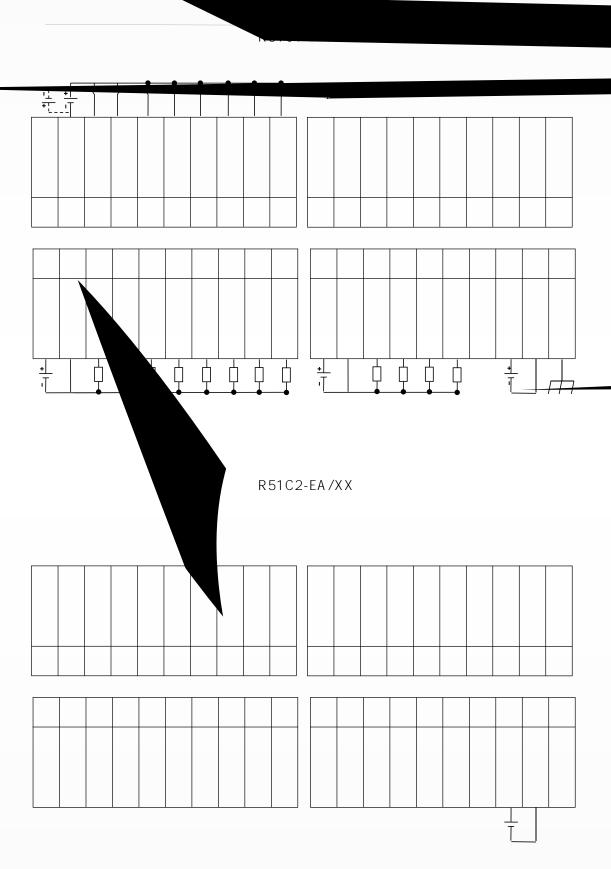
3.1



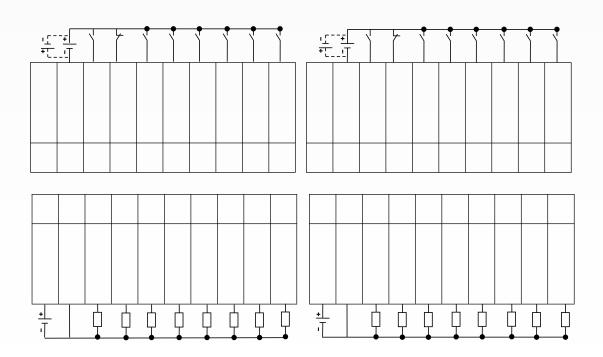
1



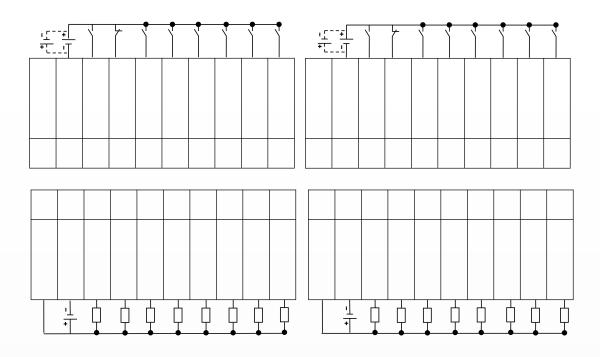


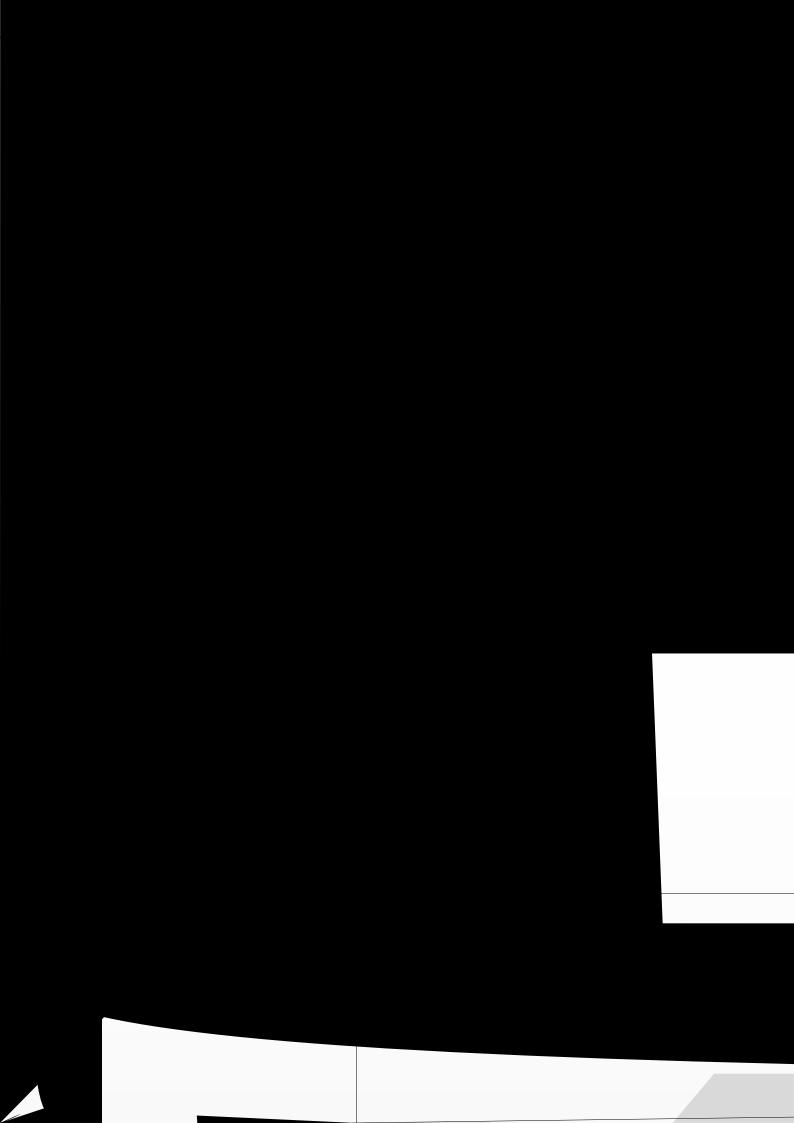


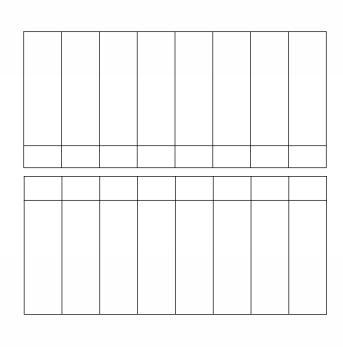
R5201-EA/XX



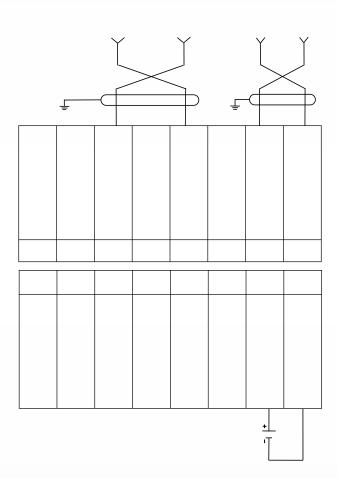
R5202-EA/XX



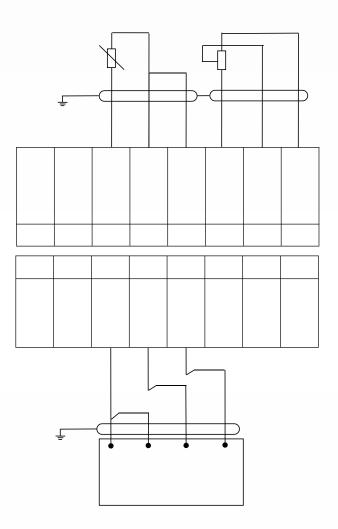




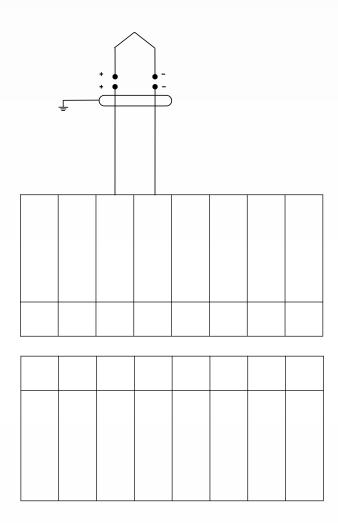
E4041



E8041



E8042

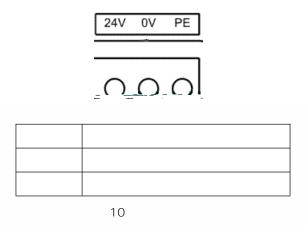




LINK1/LINK2	ACT1/ACT2	
0		
	0	
	0	

9 RJ45

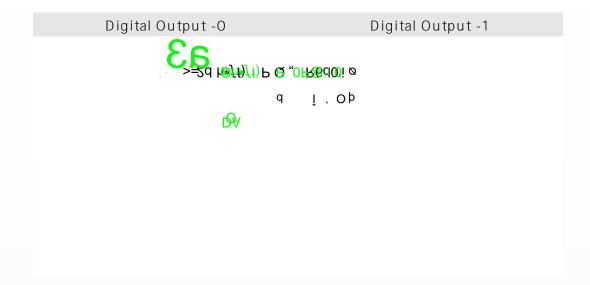
4.6



DI[0.0~0.7]	DI[1.0~1.7]
000034367	0901234567

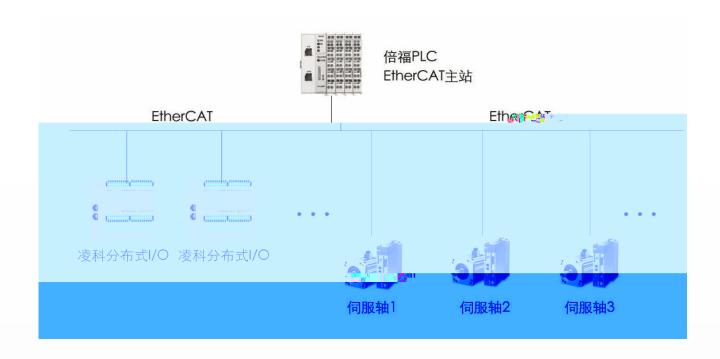
Digital Input-0	Digital Input-1				







5.1 ETHERCATIO

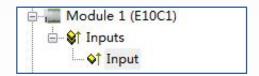


3:ETHERCAT IO

5.2

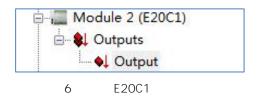
5.2.1 R51C1-EA/F R51C1-EA/Pro

5.3.1 DI



5 E10C1

5.3.2 DQ



5.3.3 AI



± 8010:0 RO Param_list ± 8011:0 Param_Offset RO 3013:0 + 8012:0 RO Param_Gain RO Param_AverageNum E3041 SDO 8010 8

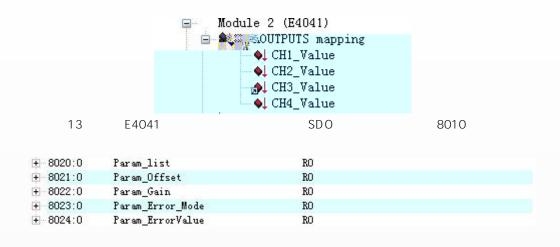
E 8010:0	Param_list	RO
8010:01	CH1_Range	RW P
8010:02	CH2_Range	RW P
8010:03	CH3_Range	RW P
8010:04	CH4_Range	Fig.()/

⊟ 8011:0	Param_Offset	RO	
8011:01	CH1_Offset	RW P	<u></u> -
8011:02	CH2_Offset	RW P	2008
8011:03	CH3_Offset	RW P	2223
8011:04	CH4 Offset	RW P	

8012:0	Param_Gain		R	0			
8012:01	CH1_Gain		R	W P	3 50 50		
8012:02	CH2_Gain		R	W P	\$ <u>0.52</u>		
8012:03	CH3_Gain		R	W P			
8012:04	CH4_Gain	300	RW P			38	

8013:0	Param_AverageNum	RO			
8013:01	CH1_AverageNum	RW	P	<u> </u>	
8013:02	CH2_AverageNum	RW	P	2008	
8013:03	CH3_AverageNum	RW	P	2220	
8013:04	CH4_AverageNum	RW	P	200 9	

5.4.1 A O



E4041

⊟-8020:0	Param_list	RO			
8020:01	CH1_Range	RW P	127000		
8020:02	CH2_Range	RW P	3000		
8020:03	CH3_Range	RW P	3202		
8020:04	CH4_Range	RW P	330-13-0		
15		SDO		8010	

8021:0	Param_Offset		RO	
8021:01	CH1_Offset		RW 👫 🔠 🕌	8021:02 0
HZ_UffS8f1 00	am acc :	KW P	var = v (i)	8021:03 0
H3_Offset				8021:04 0
H4_Offset				1.1

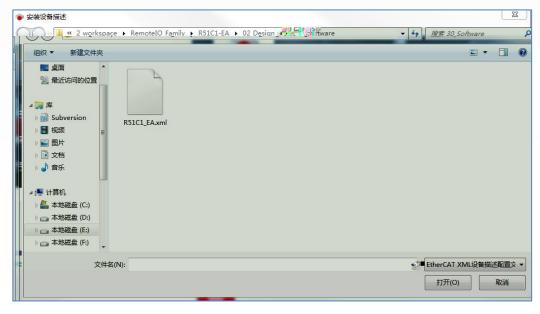
8022:0	Param_Gain	RO			
8022:01	CH1_Gain	RW	P	3222	
8022:02	CH2_Gain	RW	P	W 	
8022:03	CH3_Gain	RW	P	(
8022:04	CH4_Gain	RW	P	9 777	

5.6 XML

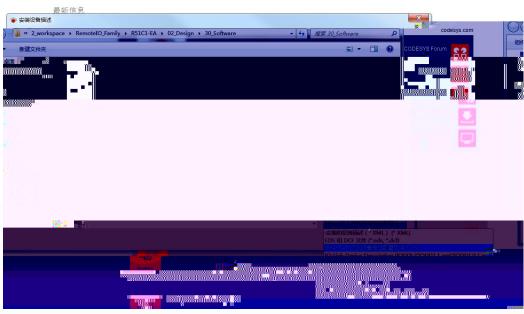
5.6.1

Twincat2

CODESYS V3.5 SP6 Patch 1



18 CODESYS



19CODESYS





